## Test Results: TIDM-WATERMETER-LCSENSOR System Power for rotation detection using ScanIF

Texas Instruments

## Power consumption using ScanIF

In the previous design using MSP430F41x, the LC sensing is realized by using external circuit as shown below. The MCU generates a pulse to the external circuit to start oscillation on the LC sensors. The oscillation is filtered and the MCU measures the signal at the sensor output. Based on the measured result, damped or un-damped of the oscillation is detected. By comparing with the previous state of the sensors, the rotation is calculated.

All of the above measurement is controlled by the MCU. During the measurement, the MCU is in active mode which consumes MCU clock cycles and causes higher power consumption.

Detailed description of this implementation can be found in the application report <u>SLAA138A</u>.





By using ScanIF in MSP430FW42x, most of the external components can be eliminated. Besides, the measurement is done by ScanIF automatically. Once the ScanIF is set up and enabled, the MCU will not involve for the measurement. The rotation is reflected as counter value inside the ScanIF. The MCU can be set to low power mode for most of the time, unless an interrupt is set for specific action such as reporting counter values. Since the MCU is freed up, there will be more MCU cycles available for other operations. If the MCU is set in low power mode, the system power consumption can be lowered significantly.

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Figure 2 - Connection of LC sensors with MSP430FW42x

The following diagram shows the power consumption of LC sensing using external discrete circuitry with MSP430F417, and using the integrated ScanIF with MSP430FW427, based on the above schematics. The power measurement is done during the test setup detecting damped or un-damped state of the oscillation at different sampling rates. It shows that the power consumption using ScanIF is lower than that using external circuitry. As sampling rate increases, the difference in power consumption between external circuitry and SancIF becomes more significant.

Sampling	Power consumption	
Rate	(uA)	
	Externa	ScanIF
	l circuitry	
25		2.40
32	5.00	
50		2.75
64	7.50	
101		3.60
128	13.50	
202		5.30
256	25.60	
390		8.44
512	49.40	
607		12.07
780		14.95
910		17.14
1092		20.15





Figure 3 - Current consumption between external discrete circuitry verses integrated ScanIF on rotation detection

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